



AUTOMATIC CONTROL SYSTEMS

(WITH MATLAB PROGRAMS)

S. Hasan Saeed



To
My Parents

Contents

1. INPUT-OUTPUT RELATIONSHIP	1.1
1.1.1 Introduction	1.1
1.1.2 Open loop control system	1.2
1.1.3 Closed loop control system	1.3
1.1.4 Comparison between open loop & closed loop	1.4
1.1.5 Block diagram representation of closed loop systems	1.5
1.1.6 Transfer function for single input single output system	1.6
1.1.7 Procedure	1.7
1.1.8 Characteristic equation of a transfer function	1.8
1.1.9 Poles and zeros of a transfer function	1.9
1.1.10 Transfer function	1.10
1.1.11 Transfer function matrix	1.11
1.1.12 Mechanical system	1.12
1.1.13 Electrical system	1.13
1.1.14 Procedure of testing the model of mechanical system	1.14
1.1.15 Analogous system	1.15
1.1.16 Mechanical-electrical network	1.16
1.1.17 Mechanical coupling	1.17
1.1.18 Block diagram representation	1.18
1.1.19 How to draw the block diagram	1.19
1.1.20 Closed loop control system	1.20
1.1.21 Multivariable multivariable system (MIMO)	1.21
1.1.22 Block diagram reduction	1.22
1.1.23 Block diagram and transfer function of a system	1.23
1.1.24 Block diagram and transfer function of a system	1.24
1.1.25 Block diagram and transfer function of a system	1.25
1.1.26 Signal flow graph	1.26
1.1.27 Construction of signal flow graph equations	1.27
1.1.28 Signal flow graph for differential equations	1.28
1.1.29 Construction of signal flow graph from block diagram	1.29
1.1.30 Mason's Gain Formula	1.30
1.1.31 Block diagram from signal flow graph	1.31
1.1.32 Block of Parameter Variation	1.32
1.1.33 Block of Parameter Variation	1.33

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Principles of Control Systems SP Eugene Xavier | J Joseph Cyril Babu, 2006 The Text book is arranged so that it can be used for self study by the engineering in practice. Included are as many examples of feedback control system in various areas of practice while maintaining a strong basic feedback control text that can be used for study in any of the various branches of engineering.

Modern Control Theory Uday A. Bakshi, Dr. Mayuresh V. Bakshi, 2020-11-01 The book is written for an undergraduate course on the Modern Control Systems. It provides comprehensive explanation of state variable analysis of linear control systems and analysis of nonlinear control systems. Each chapter starts with the background of the topic. Then it gives the conceptual knowledge about the topic dividing it in various sections and subsections. Each chapter provides the detailed explanation of the topic, practical examples and variety of solved problems. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting. The book starts with explaining the concept of state variable and state model of linear control systems. Then it explains how to obtain the state models of various types of systems using phase variables, canonical variables, Jordan's canonical form and cascade programming. Then the book includes good coverage of the matrix algebra including eigen values, eigen vectors, modal matrix and diagonalization. It also includes the derivation of transfer function of the system from its state model. The book further explains the solution of state equations including the concept of state transition matrix. It also includes the various methods of obtaining the state transition matrix such as Laplace transform method, Power series method, Cayley Hamilton method and Similarity transformation method. It further includes the detailed discussion of controllability and observability of systems. It also provides the discussion of pole placement technique of system design. The book teaches various types of nonlinearities and the nonlinear systems. The book covers the fundamental knowledge of analysis of nonlinear systems using phase plane method, isocline method and delta method. Finally it explains stability analysis of nonlinear systems and Liapunov's stability analysis.

Control Systems Engineering Salivahanan, 2015 Control Systems Engineering caters to the requirements of an interdisciplinary course on Control Systems at the under graduate level. Featuring a balanced coverage of time response and frequency response analyses, the book provides an in depth review of key topics such as components modelling techniques and reduction techniques well augmented by clear illustrations.

Control System Design Goodwin, 2001

CONTROL SYSTEMS, Second Edition KUMAR, A. ANAND, 2014-03-05 This comprehensive text on control systems is designed for undergraduate students pursuing courses in electronics and communication engineering, electrical and electronics engineering, telecommunication engineering, electronics and instrumentation engineering, mechanical engineering and biomedical engineering. Appropriate for self study, the book will also be useful for AMIE and IETE students. Written in a student friendly, readable manner, the book, now in its Second Edition, explains the basic fundamentals and concepts of control systems in a clearly understandable form. It is a balanced survey of theory aimed to provide the students with an in depth

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All the chapters are arranged in a specific sequence which helps to build the understanding of the subject in a logical fashion. The book starts with explaining the various types of control systems. Then it explains how to obtain the mathematical models of various types of systems such as electrical, mechanical, thermal, and liquid level systems. Then the book includes good coverage of the block diagram and signal flow graph methods of representing the various systems and the reduction methods to obtain simple system from the analysis point of view. The book further illustrates the steady state and transient analysis of control systems. The book covers the fundamental knowledge of controllers used in practice to optimize the performance of the systems. The book emphasizes the detailed analysis of second order systems as these systems are common in practice and higher order systems can be approximated as second order systems. The book teaches the concept of stability and time domain stability analysis using Routh Hurwitz method and root locus method. It further explains the fundamentals of frequency domain analysis of the systems including co relation between time domain and frequency domain. The book gives very simple techniques for stability analysis of the systems in the frequency domain using Bode plot, Polar plot and Nyquist plot methods. It also explores the concepts of compensation and design of the control systems in time domain and frequency domain. The classical approach loses the importance of initial conditions in the systems. Thus the book provides the detailed explanation of modern approach of analysis which is the state variable analysis of the systems including methods of finding the state transition matrix, solution of state equation and the concepts of controllability and observability. The variety of solved examples is the feature of this book which helps to inculcate the knowledge of the design and analysis of the control systems in the students. The book explains the philosophy of the subject which makes the understanding of the concepts very clear and makes the subject more interesting.

Digital Control Systems Ioan Doré Landau, Gianluca Zito, 2007-05-11. The extraordinary development of digital computers, microprocessors, microcontrollers and their extensive use in control systems in all fields of applications has brought about important changes in the design of control systems. Their performance and their low cost make them suitable for use in control systems of various kinds which demand far better capabilities and performances than those provided by analog controllers. However in order really to take advantage of the capabilities of microprocessors it is not enough to reproduce the behavior of analog PID controllers. One needs to implement specific and high performance model based control techniques developed for computer controlled systems, techniques that have been extensively tested in practice. In this context identification of a plant dynamic model from data is a fundamental step in the design of the control system. The book takes into account the fact that the association of books with software and on line material is radically changing the teaching methods of the control discipline. Despite its interactive character computer aided control design software requires the understanding of a number of concepts in order to be used efficiently. The use of software for illustrating the various concepts and algorithms helps understanding and rapidly gives a feeling of the various phenomena.

Introduction To Control Systems, An (2nd Edition) Kevin Warwick, 1996-01-31. This significantly revised

edition presents a broad introduction to Control Systems and balances new modern methods with the more classical. It is an excellent text for use as a first course in Control Systems by undergraduate students in all branches of engineering and applied mathematics. The book contains a comprehensive coverage of automatic control integrating digital and computer control techniques and their implementations, the practical issues and problems in Control System design, the three-term PID controller, the most widely used controller in industry today, numerous worked examples, and end-of-chapter exercises. This second edition also includes an introductory guide to some more recent developments, namely fuzzy logic control and neural networks.

Control Systems Engineering I. J. Nagrath, 1986

Control System Fundamentals William S. Levine, 2019-01-15

Sifting through the variety of control systems applications can be a chore. Diverse and numerous technologies inspire applications ranging from float valves to microprocessors. Relevant to any system you might use, the highly adaptable *Control System Fundamentals* fills your need for a comprehensive treatment of the basic principles of control system engineering. This overview furnishes the underpinnings of modern control systems. Beginning with a review of the required mathematics, major subsections cover digital control and modeling. An international panel of experts discusses the specification of control systems techniques for dealing with the most common and important control system nonlinearities and digital implementation of control systems with complete references. This framework yields a primary resource that is also capable of directing you to more detailed articles and books. This self-contained reference explores the universal aspects of control that you need for any application. Reliable, up-to-date, and versatile, *Control System Fundamentals* answers your basic control systems questions and acts as an ideal starting point for approaching any control problem.

Elements of Control Systems Sudhir K. Gupta, 2002

Finally, a book that fills the gap that other books leave empty. Most other textbooks on this subject were designed for students at the engineering level or for advanced students. This book was written for students just beginning their study of control systems. It is suitable for two- to four-year college programs requiring an in-depth understanding of control systems. A one-semester university course at freshman level. Industry personnel interested in developing a greater understanding of control principles. An attempt has been made to cover the major topics in control system technology. This book will help students to develop sufficient understanding to operate, maintain, and regulate control systems. At the same time, it will permit students to design and develop basic control systems. The book consists of two major sections. Part I covers control system theory, while Part II covers controllers and their applications. Schematic diagrams and in-depth descriptions of the technology help students comprehend the sometimes difficult topics of digital control, digital implementation, and fuzzy logic, and chapter questions help to reinforce the ideas presented in each chapter. An Instructor's Manual, ISBN 0 13 092866 6, is available to all instructors using the book to teach a course.

Problems & Solutions In Control System Engineering S. N. Deepa, 2005

This text provides problems and solutions of the basic control system concepts. It gives a broad and in-depth overview of solving control system problems. There are

sixteen chapters in the book Chapter 1 introduces the reader to automatic control systems Chapters 2 to 12 contain problems involving feedback control theory and the frequency domain tools of control system design Problems on non linear systems and state space analysis are solved in chapters 13 and 14 respectively Chapter 15 covers the discrete control system concept The MATLAB based control system design toolbox and the solutions to the problems programmed in MATLAB environment are discussed in chapter 16 This book will be useful for all engineering disciplines that have control system courses in their curriculum The topics included can be covered in two academic semesters The main objective of the book is to enable the students to clearly understand the method of solving control system problems *Control System Design Guide* George Ellis,2012-05-15 This title will help engineers to apply control theory to practical systems using their PC It provides an intuitive approach to controls avoiding unnecessary math and emphasising key concepts with control system models

Control System Dynamics Robert N. Clark,1996-01-26 A textbook for engineers on the basic techniques in the analysis and design of automatic control systems **Control System Design** Bernard Friedland,1987 **Control Systems** Naresh K Sinha,2008 An Introduction To Control Systems This Book Provides The Reader With The Basic Concepts Of Control Theory As Developed Over The Years In Both The Frequency Domain And The Time Domain The Opening Chapters Of The Book Present A Unified Treatment Of Modelling Of Dynamic Systems The Classical Material On The Performance Of Feedback Systems Based On The Transfer Function Approach And The Stability Of Linear Systems Further Various Types Of Frequency Response Plots And The Compensation Of Control Systems Have Been Presented In Particular The Trial And Error Approach To The Design Of Lead Compensators As Found In Most Textbooks Has Been Replaced By A Direct Method Developed In The Late 1970S Moreover The Design Of Pole Placement Compensators Using Transfer Functions The Counterpart Of The Combined Observer And State Feedback Controller Has Been Included For The First Time In A Book Appropriate For Undergraduate And Practicing Engineers In This Third Edition The Scheme For Pole Placement Compensation Has Been Made Consistent With That In Chapter 12 The Chapter On Digital Control A Rapidly Developing And Popular Area Has Been Dealt With In An Up To Date Manner This Book Is An Attempt To Aid The Student Remove The Drudgery Out Of Numerical Computations Along With Numerous Worked Examples And Drill Problems With Answers To Help The Student In Mastering The Subject *Control Systems Engineering* A. Nagoor Kani,2020-03-30 This book presents topics in an easy to understand manner with thorough explanations and detailed illustrations to enable students to understand the basic underlying concepts The fundamental concepts graphs design and analysis of control systems are presented in an elaborative manner Throughout the book carefully chosen examples are given so that the reader will have a clear understanding of the concepts Control System Components John Egan Gibson,Franz B. Tuteur,2013-03

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