



Discrete Sliding Mode Control For Robust Tracking Of Time

Michael Seilmaier



Discrete Sliding Mode Control For Robust Tracking Of Time:

Sliding Mode Control Using Novel Sliding Surfaces B. Bandyopadhyay, Fulwani Deepak, Kyung-Soo Kim, 2009-09-23
After a survey paper by Utkin in the late 1970s sliding mode control methodologies emerged as an effective tool to tackle uncertainty and disturbances which are inevitable in most of the practical systems Sliding mode control is a particular class of variable structure control which was introduced by Emel'yanov and his colleagues The design paradigms of sliding mode control has now become a mature design technique for the design of robust controller of uncertain system In sliding mode technique the state trajectory of the system is constrained on a chosen manifold or within some neighborhood thereof by an appropriate control action This manifold is also called a switching surface or a sliding surface During sliding mode system dynamics is governed by the chosen manifold which results in a well celebrated invariance property towards certain classes of disturbance and model mismatches The purpose of this monograph is to give a different dimension to sliding surface design to achieve high performance of the system Design of the switching surface is vital because the closed loop dynamics is governed by the parameters of the sliding surface Therefore sliding surface should be designed to meet the closed loop specifications Many systems demand high performance with robustness To address this issue of achieving high performance with robustness we propose nonlinear surfaces for different classes of systems The nonlinear surface is designed such that it changes the system's closed loop damping ratio from its initial low value to a final high value

Proceedings of the 2009 International Conference on Signals, Systems and Automation (ICSSA 2009) Himanshu Soni, 2010-04-30 This book is a collection of papers from the 2009 International Conference on Signals Systems and Automation ICSSA 2009 The conference at a glance Pre-conference Workshops Tutorials on 27th Dec 2009 Five Plenary talks Paper Poster Presentation 28-29 Dec 2009 Demonstrations by SKYVIEW Inc SLS Inc BSNL Baroda Electric Meters SIS On-line paper submission facility on website 200 papers are received from India and abroad Delegates from different countries including Poland Iran USA Delegates from 16 states of India Conference website is seen by more than 3000 persons across the world 27 countries and 120 cities

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The 8th International Conference on Robotic, Vision, Signal Processing & Power Applications Harsa Amylia Mat Sakim,Mohd Tafir Mustaffa,2014-07-08 The proceeding is a collection of research papers presented at the 8th International Conference on Robotics Vision Signal Processing and Power Applications ROVISIP 2013 by researchers scientists engineers academicians as well as industrial professionals from all around the globe The topics of interest are as follows but are not limited to Robotics Control Mechatronics and Automation Vision Image and Signal Processing Artificial Intelligence and Computer Applications Electronic Design and Applications Telecommunication Systems and Applications Power System and Industrial Applications

Advances in Neural Networks -- ISSN 2011 Derong Liu,Huaguang Zhang,Marios Polycarpou,Cesare Alippi,Haibo He,2011-05-10 The three volume set LNCS 6675 6676 and 6677 constitutes the refereed proceedings of the 8th International Symposium on Neural Networks ISSN 2011 held in Guilin China in May June 2011 The total of 215 papers presented in all three volumes were carefully reviewed and selected from 651 submissions The contributions are structured in topical sections on computational neuroscience and cognitive science neurodynamics and complex systems stability and convergence analysis neural network models supervised learning and unsupervised learning kernel methods and support vector machines mixture models and clustering visual perception and pattern recognition motion tracking and object recognition natural scene analysis and speech recognition neuromorphic hardware fuzzy neural networks and robotics multi agent systems and adaptive dynamic programming reinforcement learning and decision making action and motor control adaptive and hybrid intelligent systems neuroinformatics and bioinformatics information retrieval data mining and knowledge discovery and natural language processing

Automation 2021: Recent Achievements in Automation, Robotics and Measurement Techniques Roman Szewczyk,Cezary Zieliński,Małgorzata Kaliczyńska,2021-04-29 This book contains 38 papers authored by both scientists and practitioners focused on an interdisciplinary approach to the development of cyber physical systems Recently our civilization has been facing one of the most severe challenges in modern history The COVID 19 pandemic devastated the global economy and significantly disrupted numerous areas of economic activity Only radical increase of efficiency and versatility of industrial production with further limitation of human involvement paralleled by the decrease of environmental burden will enable us to cope with such challenges We hope that the presented book provides input to the solution of at least some problems brought about by this challenge This approach relies on the development of measuring techniques robotic and mechatronic systems industrial automation numerical modeling and simulation as well as application of artificial intelligence techniques required by the transformation leading to Industry 4 0

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