

BALL AND BEAM 1: Basics

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ABSTRACT: This is one of a series of white papers on systems modelling, analysis and control, prepared by Control Systems Principles.co.uk to give insights into important principles and processes in control. In control systems there are a number of generic systems and methods which are encountered in all areas of industry and technology. These white papers aim to explain these important systems and methods in straightforward terms. The white papers describe what makes a particular type of system/method important, how it works and then demonstrates how to control it. The control demonstrations are performed using models of real systems that I designed, and which have been developed for manufacture by TQ Education and Training Ltd in their CE range of equipment. This white paper is about a very useful and influential laboratory system for teaching control of unstable systems – the Ball and Beam System.

1. What is the Ball and Beam?

The ball and beam system is one of the most enduringly popular and important laboratory models for teaching control systems engineering. The ball and beam system is widely used because it is very simple to understand as a system, and yet the control techniques that can be studied it cover many important classical and modern design methods. It has a very important property – it is open loop unstable.

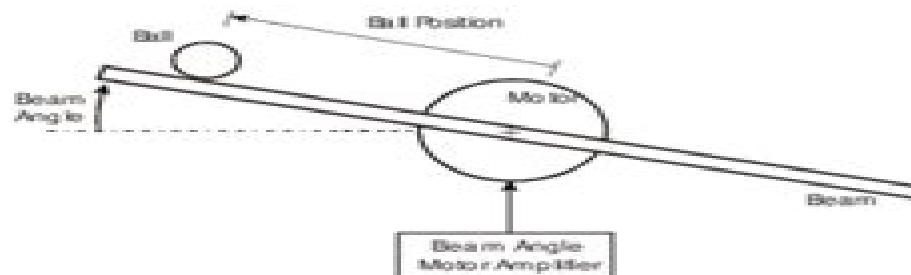


Figure 1. The Ball and Beam System.

The system (shown in figure 1) is very simple – a steel ball rolling on the top of a long beam. The beam is mounted on the output shaft of an electric motor and so the beam can be tilted about its centre axis by applying an electrical control signal to the motor amplifier. The position of the ball on the beam can be measured using a special sensor.

The control job is to automatically regulate the position of the ball on the beam by changing the angle of the beam. This is a difficult control task because the ball does not stay in one place on the beam but moves with an acceleration that is proportional to the tilt of the beam. In control technology the system is open loop unstable because the system output (the ball position) increases without limit for a fixed input (beam angle). Feedback control must be used to keep the ball in a desired position on the beam.

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Lei Huang



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Scientific and Technical Aerospace Reports ,1968 *Basics of Missile Guidance and Space Techniques* Marvin Hobbs,1959 **Advanced Industrial Control Technology** Peng Zhang,2010-08-26 Control engineering seeks to understand physical systems using mathematical modeling in terms of inputs outputs and various components with different behaviors It has an essential role in a wide range of control systems from household appliances to space flight This book provides an in depth view of the technologies that are implemented in most varieties of modern industrial control engineering A solid grounding is provided in traditional control techniques followed by detailed examination of modern control techniques such as real time distributed robotic embedded computer and wireless control technologies For each technology the book discusses its full profile from the field layer and the control layer to the operator layer It also includes all the interfaces in industrial control systems between controllers and systems between different layers and between operators and systems It not only describes the details of both real time operating systems and distributed operating systems but also provides coverage of the microprocessor boot code which other books lack In addition to working principles and operation mechanisms this book emphasizes the practical issues of components devices and hardware circuits giving the specification parameters install procedures calibration and configuration methodologies needed for engineers to put the theory into practice Documents all the key technologies of a wide range of industrial control systems Emphasizes practical application

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Table of Contents Ball And Beam 1 Basics Control Systems Principles

1. Understanding the eBook Ball And Beam 1 Basics Control Systems Principles
 - The Rise of Digital Reading Ball And Beam 1 Basics Control Systems Principles
 - Advantages of eBooks Over Traditional Books
2. Identifying Ball And Beam 1 Basics Control Systems Principles
 - Exploring Different Genres
 - Considering Fiction vs. Non-Fiction
 - Determining Your Reading Goals
3. Choosing the Right eBook Platform
 - Popular eBook Platforms
 - Features to Look for in an Ball And Beam 1 Basics Control Systems Principles
 - User-Friendly Interface
4. Exploring eBook Recommendations from Ball And Beam 1 Basics Control Systems Principles
 - Personalized Recommendations
 - Ball And Beam 1 Basics Control Systems Principles User Reviews and Ratings

- Ball And Beam 1 Basics Control Systems Principles and Bestseller Lists
- 5. Accessing Ball And Beam 1 Basics Control Systems Principles Free and Paid eBooks
 - Ball And Beam 1 Basics Control Systems Principles Public Domain eBooks
 - Ball And Beam 1 Basics Control Systems Principles eBook Subscription Services
 - Ball And Beam 1 Basics Control Systems Principles Budget-Friendly Options
- 6. Navigating Ball And Beam 1 Basics Control Systems Principles eBook Formats
 - ePub, PDF, MOBI, and More
 - Ball And Beam 1 Basics Control Systems Principles Compatibility with Devices
 - Ball And Beam 1 Basics Control Systems Principles Enhanced eBook Features
- 7. Enhancing Your Reading Experience
 - Adjustable Fonts and Text Sizes of Ball And Beam 1 Basics Control Systems Principles
 - Highlighting and Note-Taking Ball And Beam 1 Basics Control Systems Principles
 - Interactive Elements Ball And Beam 1 Basics Control Systems Principles
- 8. Staying Engaged with Ball And Beam 1 Basics Control Systems Principles
 - Joining Online Reading Communities
 - Participating in Virtual Book Clubs
 - Following Authors and Publishers Ball And Beam 1 Basics Control Systems Principles
- 9. Balancing eBooks and Physical Books Ball And Beam 1 Basics Control Systems Principles
 - Benefits of a Digital Library
 - Creating a Diverse Reading Collection Ball And Beam 1 Basics Control Systems Principles
- 10. Overcoming Reading Challenges
 - Dealing with Digital Eye Strain
 - Minimizing Distractions
 - Managing Screen Time
- 11. Cultivating a Reading Routine Ball And Beam 1 Basics Control Systems Principles
 - Setting Reading Goals Ball And Beam 1 Basics Control Systems Principles
 - Carving Out Dedicated Reading Time
- 12. Sourcing Reliable Information of Ball And Beam 1 Basics Control Systems Principles
 - Fact-Checking eBook Content of Ball And Beam 1 Basics Control Systems Principles
 - Distinguishing Credible Sources

13. Promoting Lifelong Learning
 - Utilizing eBooks for Skill Development
 - Exploring Educational eBooks
14. Embracing eBook Trends
 - Integration of Multimedia Elements
 - Interactive and Gamified eBooks

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web jun 4 2013 economics and business advanced subsidiary unit 2b business economics 6eb02 01 tuesday 4 june 2013 morning time 1 hour 15 minutes instructions tt use black ink or ball point pen fill in the boxes at the top of this page with your name centre number and candidate number t t answer all questions in section a and section b