

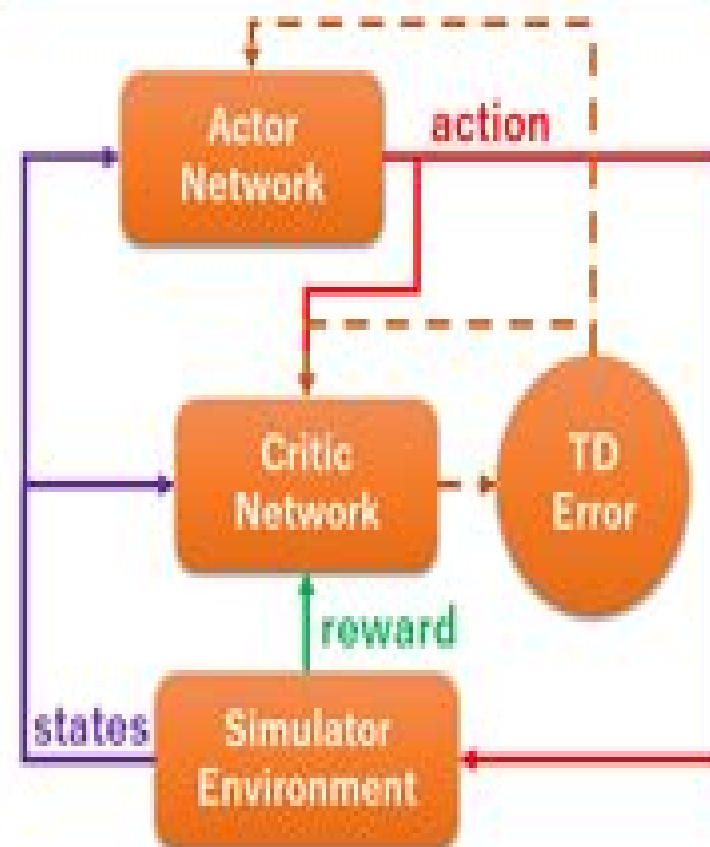
# Mobile Robot Obstacle Avoidance by Reinforcement Learning

- Objective: Avoiding any obstacle while pursuing a goal point

## Robot



## Learning Algorithm (DDPG)



# Decentralized Reinforcement Learning Applied To Mobile Robots

**Raffaela Di Napoli**



## **Decentralized Reinforcement Learning Applied To Mobile Robots:**

*RoboCup 2016: Robot World Cup XX* Sven Behnke, Raymond Sheh, Sanem Sariel, Daniel D. Lee, 2017-11-01 This book includes the post conference proceedings of the 20th RoboCup International Symposium held in Leipzig Germany in July 2016 In addition to the 38 contributions to the symposium selected from 63 submissions the book also contains 15 champion papers of teams winning individual leagues of the RoboCup 2016 competition the Amazon Picking Challenge and the Harting Open Source Award The papers present current research in the fields of robotics and artificial intelligence with a special focus to robot hardware and software environment perception action planning and control robot learning multi robot systems and human robot interaction

*RoboCup 2017: Robot World Cup XXI* Hidehisa Akiyama, Oliver Obst, Claude Sammut, Flavio Tonidandel, 2018-09-12 This book includes the post conference proceedings of the 21st RoboCup International Symposium held in Nagoya Japan in September 2017 The 33 full revised papers and 9 papers from the winning teams presented were carefully reviewed and selected from 58 submissions The papers are organized on topical sections on Robotics Artificial intelligence Environment perception State estimation and much more

Sensor Fusion and Decentralized Control in Autonomous Robotic Systems Paul S. Schenker, G. T. McKee, 1997

Sensor Fusion and Decentralized Control in Robotic Systems, 2001

**Strategies for Collective Minimalist Mobile Robots** Chris Melhuish, 2001-04-11 Many might think that the robot industry is not ready yet to build an abstract painter with a political theory Perhaps Melhuish engineering U of the West of England agrees because what he talks about instead is the idea of getting a whole lot of dumb robots to work together to accomplish something smart The inspiration for the approach are social insects which are limited individually yet can as a group achieve remarkable feats He presents minimalist strategies for controlling and coordinating such a system in the domains of moving through the environment creating work gangs of a desired size and acting on the environment Distributed in the US by ASME c Book News Inc

*Unmanned Ground Vehicle Technology*, 2001

**Robot Teams** Tucker Balch, Lynne E. Parker, 2002-04-17 This reference on multi robot systems explains the essentials of multi agent robotics theory and describes particular systems illustrating the major concepts of multi robot research Each chapter represents a key concept or design approach which has advanced the field of robotic research and development especially in the area of cooperation among robots Descriptions are augmented with mathematical formulations photographs diagrams and source code Balch teaches at Georgia Tech University Parker is affiliated with the Oak Ridge National Laboratory Annotation copyrighted by Book News Inc Portland OR

**Index to IEEE Publications** Institute of Electrical and Electronics Engineers, 1997

*Computer & Control Abstracts*, 1996

**1998 IEEE International Conference on Evolutionary Computation Proceedings** IEEE Neural Networks Council, 1998 This collection of papers from the ICEC conference covers a wide range of aspects of evolutionary computing This includes principles of evolutionary computation such as adaptation and self adaption variation operators representational issues and theoretical investigations

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**Abstracts** ,1999      **Proceedings of the ... IEEE Conference on Evolutionary Computation** ,1998      **Proceedings** ,1997      **The Engineering Index Annual** ,1992 Since its creation in 1884 Engineering Index has covered virtually every major engineering innovation from around the world It serves as the historical record of virtually every major engineering innovation of the 20th century Recent content is a vital resource for current awareness new production information technological forecasting and competitive intelligence The world s most comprehensive interdisciplinary engineering database Engineering Index contains over 10 7 million records Each year over 500 000 new abstracts are added from over 5 000 scholarly journals trade magazines and conference proceedings Coverage spans over 175 engineering disciplines from over 80 countries Updated weekly      **IROS** ,1992      **NeuralSource** Philip D. Wasserman,Roberta M. Oetzel,1990 Derived from the database Neural Base still available at 495 00 this bibliography covering more than 4 000 references is an important collection of research information Extensive annotations have been added to approximately 75% of the entries in the print version Periodicals private reports and books are included Indexed by author keyword and publication Neurons were slacking off when A mathematical theory was indexed under A Annotation copyrighted by Book News Inc Portland OR

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