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Shelley, 1990 Books in Print Supplement , 1994 *Statics and Structural Mechanics* Omprakash Beniwal, 2025-02-20

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Catalog of Copyright Entries. Third Series Library of Congress. Copyright Office,1976 *Theory of Gyroscopic Effects for Rotating Objects* Ryspek Usubamatov,2022-06-30 This book highlights an analytical solution for the dynamics of axially rotating objects It also presents the theory of gyroscopic effects explaining their physics and using mathematical models of Euler s form for the motion of movable spinning objects to demonstrate these effects The major themes and approaches are represented by the spinning disc and the action of the system of interrelated inertial torques generated by the centrifugal and Coriolis forces as well as the change in the angular momentum The interrelation of inertial torques is based on the dependency of the angular velocities of the motions of the spinning objects around axes by the principle of mechanical energy conservation These kinetically interrelated torques constitute the fundamental principles of the mechanical gyroscope theory that can be used for any rotating objects of different designs like rings cones spheres paraboloids propellers etc Lastly the mathematical models for the gyroscopic effects are validated by practical tests The 2nd edition became necessary due to new development and corrections of mathematical expressions It contains new chapters about the Tippe top inversion and inversion of the spinning object in an orbital flight and the boomerang aerodynamics

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conference proceedings of the 2nd International Conference on Modern Problems of Robotics MPoR 2020 held in Moscow Russia in March 2020 The 16 revised full papers were carefully reviewed and selected from 21 submissions The volume includes the following topical sections Collaborative Robotic Systems Robotic Systems Design and Simulation and Robots Control The papers are devoted to the most interesting today s investigations in Robotics such as the problems of the human robot interaction the problems of robot design and simulation and the problems of robot and robotic complexes control

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